

FOLD DRONE

INSTRUCTION FOR USE

AGES 14+

Voltage and current requirements for USB charging lines

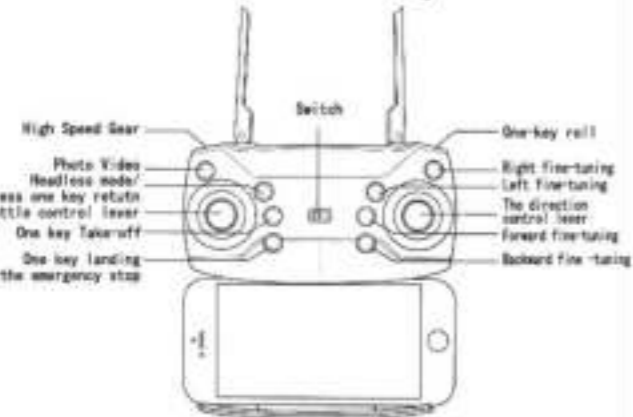
Input voltage	DC5V 7-5.3V
Adapter current	0.5-2A

Attention:
The input voltage and current of USB charging line must not exceed this standard. No three-load adapter is allowed. Otherwise, the USB charging line and battery will be damaged.

The knowledge and safety notes below are useful for you in the remote control use. Please read this manual carefully before operating this product and keep it for further reference.

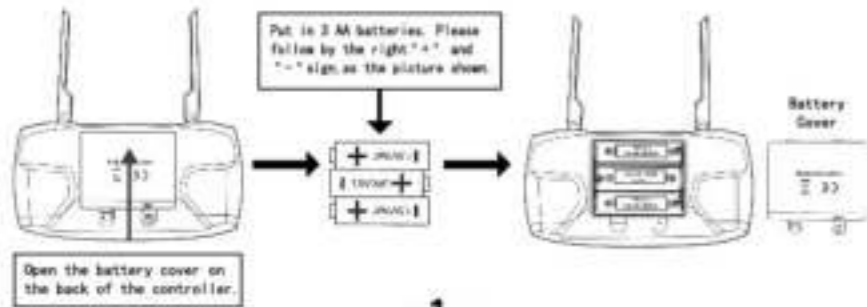


USB charge cable X1



1. THE INSTALLATION OF BATTERY OF REMOTE CONTROL DEVICE

Open the battery cover on the back of remote controller. Insert 3X1.5V "AA" batteries in accordance with the instructions on battery box. (Battery should be purchased separately, old and new or different types of batteries shouldn't be mixed.)



Open the battery cover on the back of the controller.

2. THE BATTERY CHARGING OF FLYING DEVICE

- 1 Insert USB charger into the USB interface on the computer or other chargers and then plug in, the indicator light will be on.
- 2 Remove the battery from the aircraft, and then connect the battery plug to the socket on the USB charger for charging.
- 3 The indicator light will be on in the battery charging process and will be off after charging saturation.



Note: The charging time is about 120 minutes.

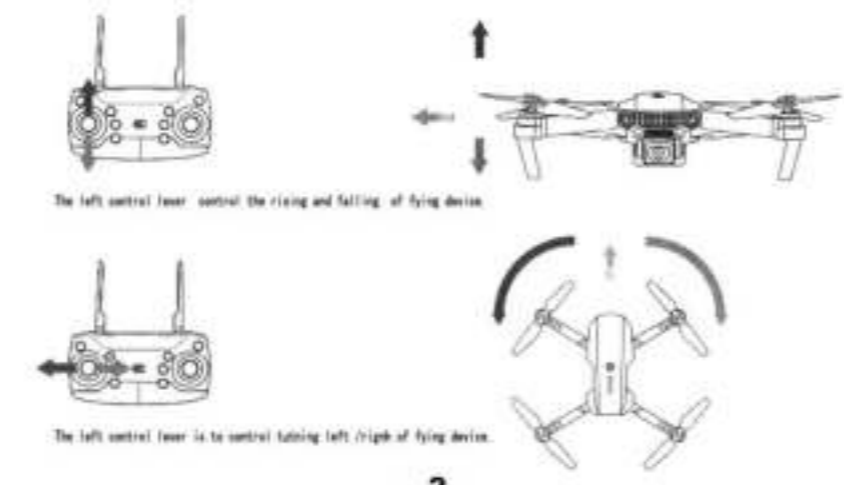
3. Built-in camera

4. THE OPERATION AND CONTROL OF FLYING DEVICE

Note: After takeoff, please first correct the Forward Aircraft Light. Flashing when the correction is completed after the lights (1) to indicate of unsuitable when flying device needs to pay attention on the operating time carefully in the process of operation. The time may last a little more. You'd better to add power to search of operation. The time may last a little more.

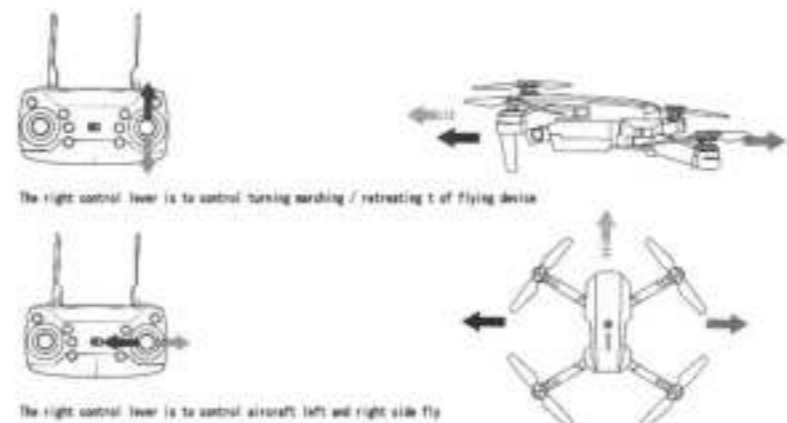


Flank folding



The left control lever control the rising and falling of flying device.

The left control lever is to control turning left /right of flying device.

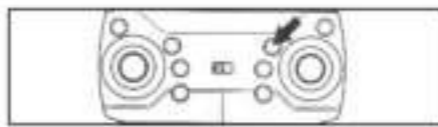


The right control lever is to control turning marking / retracting t of flying device.

The right control lever is to control aircraft left and right side fly

5. FINE-ADJUSTMENT

When the flying device is in the flight, it appears deviation (turning left/right, marking/retracting left/right side). It is to adjust them by turning the operation direction corresponding right keys. For example, the flying device is deviated to front, so it is to adjust by turning the backward "marking/retracting right" key as shown in figure.



6. THE SETTINGS OF SENSITIVITYM

The aircraft can achieve the 2 modes of operation: low level (30%), high level (100%)
Toggle "speed conversion switch" for setting:
Slide it, the buzzer on remote controller will heat once = The aircraft moves at a low speed (up to 30%);
Slide it, the buzzer on remote controller will heat two times = The aircraft moves at a high speed (up to 100%).

Through this key, it can adjust sensitivity of flying device, the greater the sensitivity value is, the faster the flying device response, conversely it is slower.

7. THE ROLLING MODEL

The flying device can perform rolling flight of 360 degrees by following operation. In order to better implement rolling function, and ensure flying device is kept five meters height above the ground, it is better to operate rolling in the process of rising up. In this case, the flying device can be kept with height after flying device performs rolling action.



1 Left side somersault: Click "mode of conversion", and then push the right-control lever to left in maximum. After the flying device rolls it is to turn control lever to the middle position.

2 Right side somersault: Click "mode of conversion" and then push the right-control lever to right in maximum. After the flying device rolls, it is to turn control lever to the middle position.



AFTER ENTERING INTO THE "ROLL MODE", IF THERE IS NO NEED OF ROLLING FUNCTIONS, THEN CLICK THE "MODE CONVERSION" KEY

8. HEADLESS MODE WITH ONE KEY RETURN

This is in flight, no matter what position the aircraft is, no matter what direction it's made, as long as you click on the headless mode button, automatic locking direction aircraft takeoff. When found in aircraft flight has left you very far when you could not tell the direction, then click on the headless mode key, you can not recognize the direction to control the aircraft return, return key or click the auto return function of the vehicle will automatically return.
1 At the side of the aircraft must head toward the front (or rear headless mode and automatic mode opening direction will return disorder).
2 When you need to use the headless mode, click on the headless mode key, the vehicle will automatically lock the direction of takeoff.
3 When you do not use the headless mode, then click the headless mode button to exit the headless mode.
4 When you want to automatically return, click the button to automatically return the aircraft is in the direction of takeoff will be automatically returned.
5 Automatic return process can be controlled manually about the direction of the aircraft, pushing the joystick forward to exit automatic return function.
Note: Try to choose less vision and pedestrians at the place with this aircraft, so as to avoid unnecessary losses!

9. TROUBLE SHOOTING DURING FLIGHT

Situation	Cause	Way to deal
1 Receiver does not bind continuously for more than 4 seconds after flight vehicle's battery inserted. No response to control input.	Unable to bind to transmitter.	Repeat the power up initializing process.
2 No response after battery is connected to flight vehicle.	1. Poor to transmit and receiver. 2. Check transmitter and receiver voltage. 3. Poor contact at battery terminals.	1. Turn on transmitter and ensure flight vehicle battery is inserted properly. 2. Use fully charged batteries. 3. Re-seat the battery and ensure good contact between battery contacts.
3 Motor does not respond to throttle stick, receiver LED flashes.	Flight vehicle battery depleted.	Fully charge the battery, or replace with a fully charged battery.
4 Main rotor spins but unable to take off.	1. Deformed main blades. 2. Flight vehicle battery depleted.	1. Replace main blades. 2. Charge or replace with fully charged battery.
5 Strong vibration of flight vehicle.	1. Deformed main blades.	1. Replace main blades.
6 Tail still off trim after trim adjustment, or inconsistent speed during flight.	1. Damaged tail rotor. 2. Damaged tail drive motor.	1. Replace main blades. 2. Replace the main motor.
7 Flight vehicle still wobbles forward after trim adjustment during low.	1. Gyroscope midpoint not.	1. The book will lift, fine-tune the normalized neutral point, reboot.
8 Flight vehicle still wobbles left/right after trim adjustment during low.	1. Motor off 2. Core loose	1. Replace the motor 2. Installed tight core

现象	原因	对策
1. 飞行器起飞时抖动	1. 飞行器与接收机未对准接收机 2. 接收机未对准接收机 3. 接收机未对准接收机	1. 调整接收机与接收机对准接收机 2. 调整接收机与接收机对准接收机 3. 调整接收机与接收机对准接收机
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4. 飞行器起飞时抖动	1. 飞行器与接收机未对准接收机 2. 接收机未对准接收机 3. 接收机未对准接收机	1. 调整接收机与接收机对准接收机 2. 调整接收机与接收机对准接收机 3. 调整接收机与接收机对准接收机
5. 飞行器起飞时抖动	1. 飞行器与接收机未对准接收机 2. 接收机未对准接收机 3. 接收机未对准接收机	1. 调整接收机与接收机对准接收机 2. 调整接收机与接收机对准接收机 3. 调整接收机与接收机对准接收机
6. 飞行器起飞时抖动	1. 飞行器与接收机未对准接收机 2. 接收机未对准接收机 3. 接收机未对准接收机	1. 调整接收机与接收机对准接收机 2. 调整接收机与接收机对准接收机 3. 调整接收机与接收机对准接收机
7. 飞行器起飞时抖动	1. 飞行器与接收机未对准接收机 2. 接收机未对准接收机 3. 接收机未对准接收机	1. 调整接收机与接收机对准接收机 2. 调整接收机与接收机对准接收机 3. 调整接收机与接收机对准接收机
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9. 如何排除飞行中的状况

1. 飞行器起飞时抖动: 检查接收机与接收机是否对准接收机, 接收机未对准接收机, 接收机未对准接收机。
2. 飞行器起飞时抖动: 检查接收机与接收机是否对准接收机, 接收机未对准接收机, 接收机未对准接收机。
3. 飞行器起飞时抖动: 检查接收机与接收机是否对准接收机, 接收机未对准接收机, 接收机未对准接收机。
4. 飞行器起飞时抖动: 检查接收机与接收机是否对准接收机, 接收机未对准接收机, 接收机未对准接收机。
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7. 飞行器起飞时抖动: 检查接收机与接收机是否对准接收机, 接收机未对准接收机, 接收机未对准接收机。
8. 飞行器起飞时抖动: 检查接收机与接收机是否对准接收机, 接收机未对准接收机, 接收机未对准接收机。

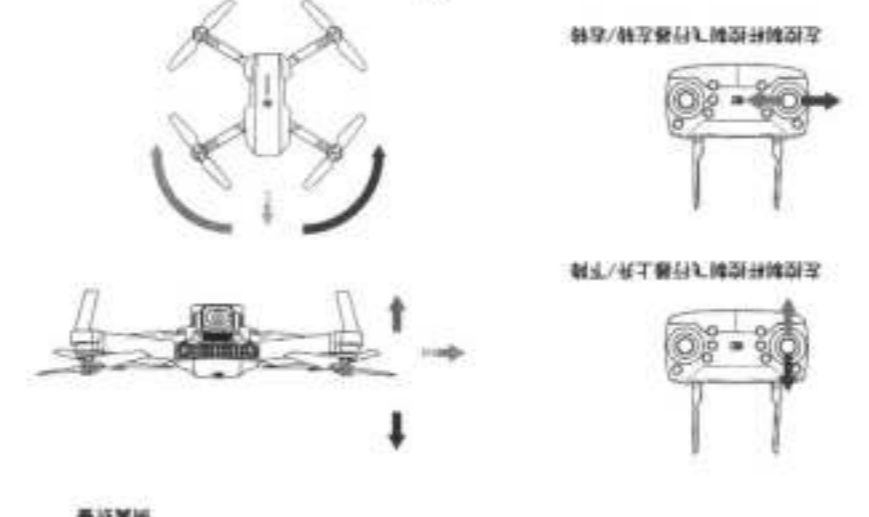
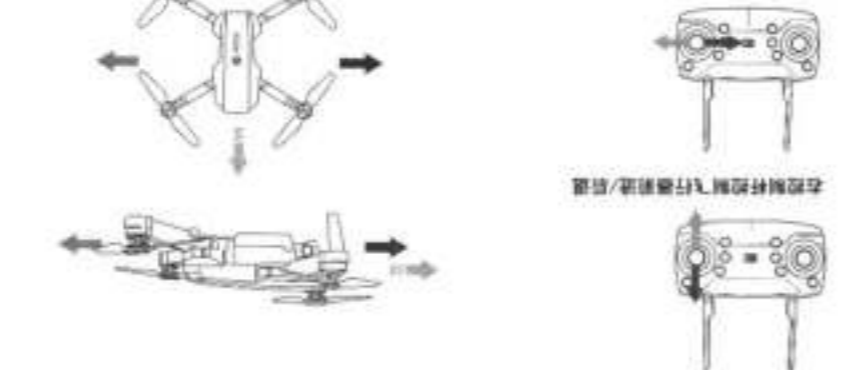
8. 无头模式与一键返航



7. 翻滚模式

1. 翻滚模式: 按下"翻滚模式"键, 飞行器将向前飞行, 飞行器将向前飞行, 飞行器将向前飞行。
2. 翻滚模式: 按下"翻滚模式"键, 飞行器将向前飞行, 飞行器将向前飞行, 飞行器将向前飞行。
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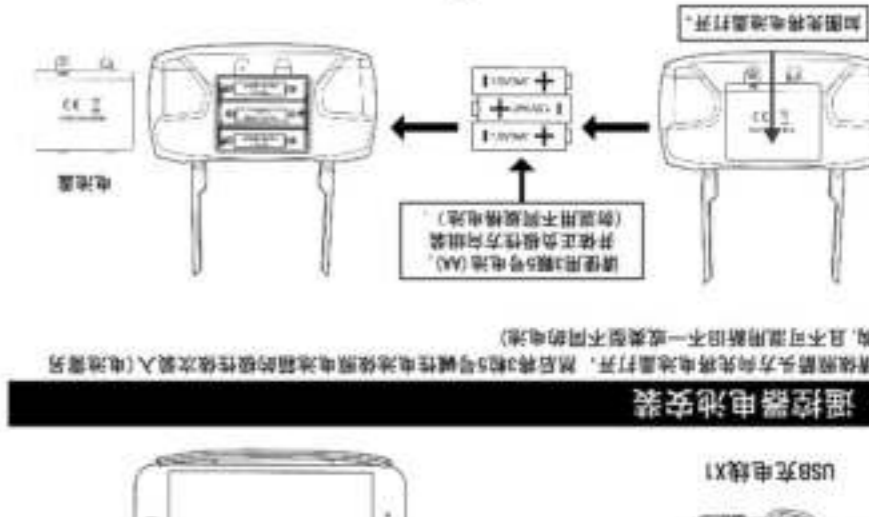
6. 慢速档调节



4. 飞行器的操作与控制

1. 飞行器起飞前: 检查接收机与接收机是否对准接收机, 接收机未对准接收机, 接收机未对准接收机。
2. 飞行器起飞时: 检查接收机与接收机是否对准接收机, 接收机未对准接收机, 接收机未对准接收机。
3. 飞行器起飞后: 检查接收机与接收机是否对准接收机, 接收机未对准接收机, 接收机未对准接收机。
4. 飞行器降落时: 检查接收机与接收机是否对准接收机, 接收机未对准接收机, 接收机未对准接收机。
5. 飞行器降落前: 检查接收机与接收机是否对准接收机, 接收机未对准接收机, 接收机未对准接收机。
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3. 内置摄像头



1. 遥控器电池安装

1. 遥控器电池安装: 将电池放入遥控器电池仓, 确保电池正负极正确。
2. 遥控器电池安装: 将电池放入遥控器电池仓, 确保电池正负极正确。
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2. 飞行器的电池充电



USB充电器电压和电流要求
输入电压: DC5V 7-5.3V
适配器电流: 0.5-2A

折疊四軸飛行器 使用說明書

適合年齡14+